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**KOLEJ YAYASAN PELAJARAN JOHOR  
FINAL EXAMINATION**

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**COURSE NAME : INSTRUMENTATION AND MEASUREMENT**  
**COURSE CODE : DEE 1053**  
**EXAMINATION : JANUARY 2024**  
**DURATION : 2 HOURS 30 MINUTES**

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**INSTRUCTION TO CANDIDATES /  
ARAHAN KEPADA CALON**

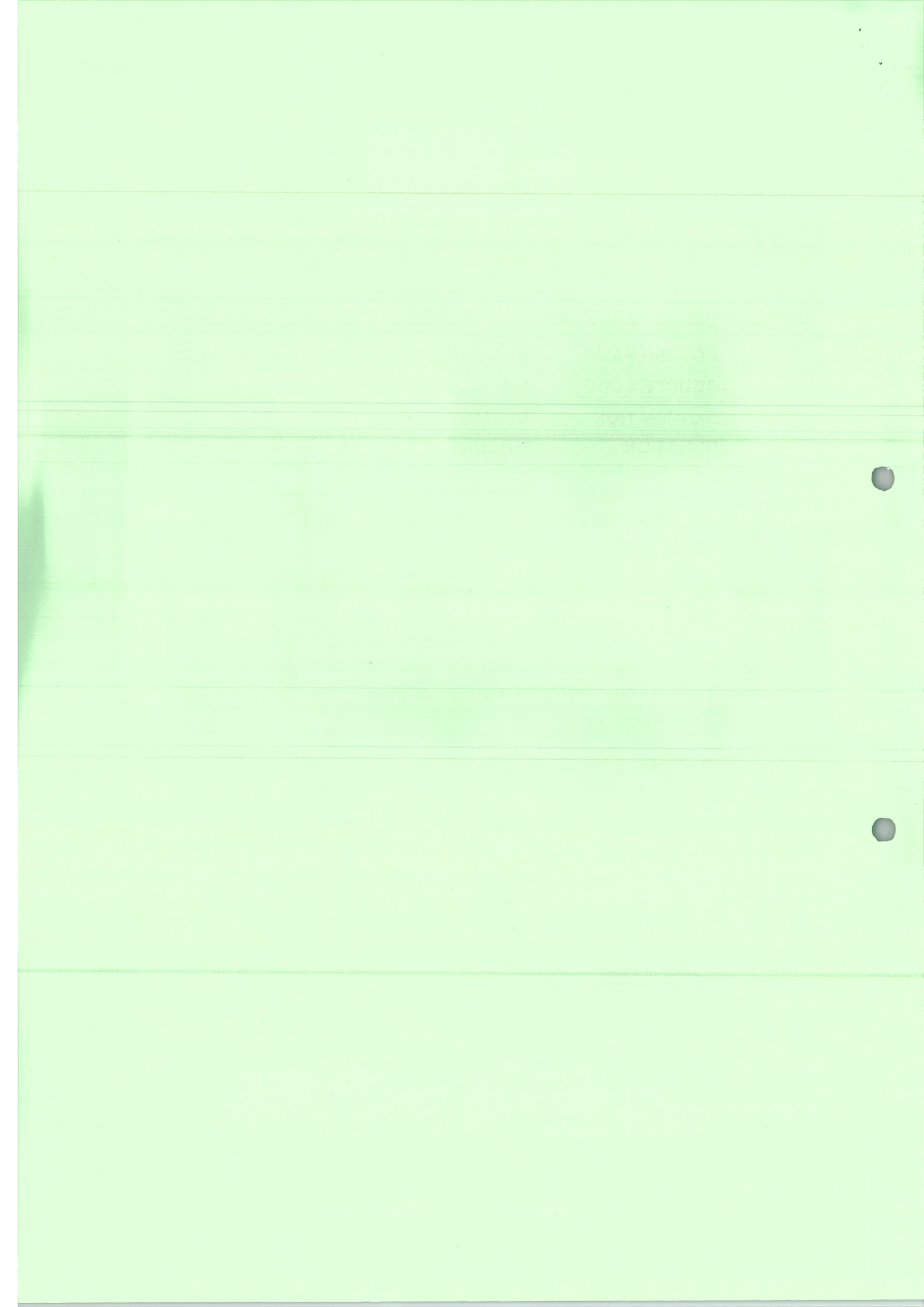
1. This examination paper consists of **FIVE (5)** questions. Answer **ALL** questions. /  
*Kertas soalan ini mengandungi LIMA (5) soalan. Jawab SEMUA soalan.*
  
2. Candidates are not allowed to bring any material/note to the examination hall/room except with the permission from the invigilator. /  
*Calon tidak dibenarkan untuk membawa sebarang bahan/nota ke dewan/bilik peperiksaan tanpa kebenaran daripada pengawas.*
  
3. Please check to make sure that this examination pack consist of: /  
*Pastikan kertas soalan peperiksaan ini mengandungi:*
  - i. The Question Paper /  
*Kertas Soalan*
  - ii. An Answering Booklet /  
*Buku Jawapan*
  - iii. Attachment 1 /  
*Lampiran 1*

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JANGAN BUKA KERTAS SOALAN INI SEHINGGA DIBERITAHU**

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This examination paper consists of **10** printed pages including front page  
*Kertas soalan ini mengandungi 10 muka surat termasuk kulit hadapan*



This part contains **FIVE (5)** questions. Answer **ALL** questions in the Answering Booklet.

*Kertas soalan ini mengandungi LIMA (5) soalan. Jawab SEMUA soalan di dalam Kertas Jawapan.*

### QUESTION 1 / SOALAN 1

- a) Analog devices are divided into **two (2)** methods of deflection. Explain the differences between the two methods.

(4 marks/ markah)

- b) Explain **two (2)** types of errors that exist in a measurement.

(4 marks/ markah)

- c) Refer to **Figure 1**. Calculate the power dissipated and the limiting error, if current  $2.0 \pm 0.01\text{A}$  flows through a  $100 \pm 0.2\Omega$  resistor.

(12 marks/ markah)

- a) *Alatan analog terbahagi kepada dua (2) kaedah pesongan. Terangkan perbezaan di antara kedua-dua kaedah tersebut.*

- b) *Terangkan dua (2) jenis ralat yang wujud dalam sesuatu pengukuran.*

- c) *Merujuk pada Rajah 1. Kirakan kuasa terlesap dan ralat mengehad, jika arus bernilai  $2.0 \pm 0.01\text{A}$  mengalir melalui perintang  $100 \pm 0.2\Omega$ .*

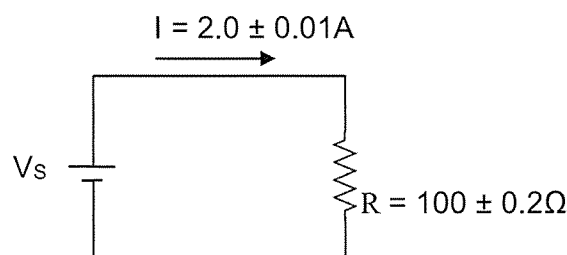


Figure 1 / Rajah 1

## QUESTION 2 / SOALAN 2

- a) A  $100 \mu\text{A}$  full scale deflection current meter movement is used in an Ayrton multi-range ampere meter circuit. The meter movement has an internal resistance,  $R_m = 2 \text{ k}\Omega$ . Determine the value of the shunt resistance, if the meter has a range of  $25 \text{ mA}$ ,  $65 \text{ mA}$  and  $100 \text{ mA}$ .

(10 marks/ markah)

- b) **Figure 2** shows a full-wave rectifier type AC meter with a range of  $1 \text{ V}$ . The diodes have a forward resistance each of  $100 \Omega$  while the parameters of the d'Arsonval movement are  $50 \mu\text{A}$ ,  $200 \Omega$ . It is required that  $I_{sh} = I_m$ .

- Calculate the shunt resistor,  $R_{sh}$ .
- Calculate the multiplier resistor,  $R_s$ .
- Calculate the AC sensitivity of the meter,  $S_{ac}$ .

(10 marks/ markah)

- a) Gerakan meter arus pesongan skala penuh  $100 \mu\text{A}$  digunakan dalam litar meter ampere berbilang julat piraou Ayrton. Gerakan meter tersebut mempunyai rintangan dalam,  $R_m = 2 \text{ k}\Omega$ . Tentukan nilai rintangan piraou, jika meter tersebut mempunyai julat  $25 \text{ mA}$ ,  $65 \text{ mA}$  dan  $100 \text{ mA}$ .

- b) **Rajah 2** menunjukkan meter AU jenis penerus penuh-gelombang berjulat  $1 \text{ V}$ . Setiap diod mempunyai rintangan ke depan  $100 \Omega$  sementara parameter gerakan d'Arsonval ialah  $50 \mu\text{A}$ ,  $200 \Omega$ . Dikehendaki supaya  $I_{sh} = I_m$ .

- Kirakan rintangan piraou,  $R_{sh}$ .
- Kirakan rintangan pendarab,  $R_s$ .
- Kirakan kepekaan AU meter,  $S_{au}$ .

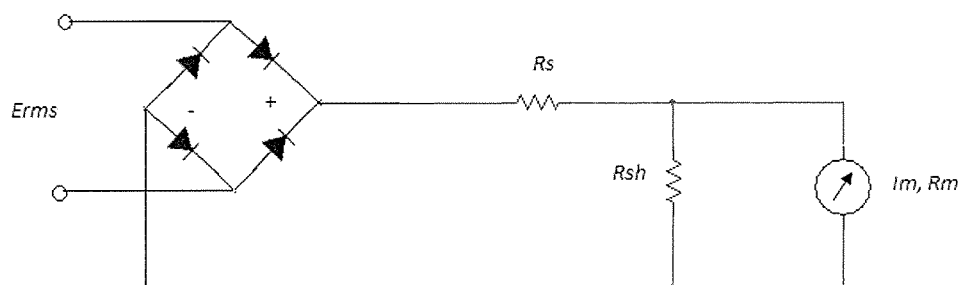


Figure 2 / Rajah 2

## QUESTION 3 / SOALAN 3

- a) Briefly explain **four (4)** advantages of a digital voltmeter as compared to an analogue voltmeter.

(12 marks/ markah)

- b) An analogue-to-digital converter uses an integrator in its input part.
- Sketch an integrator circuit with a resistor  $10\text{ k}\Omega$  and a capacitor  $10\text{ }\mu\text{F}$ .
  - If the integrator input voltage is  $1\text{ V}$ , calculate the integrator output voltage after  $0.1\text{ second}$ .
  - Sketch the form of the integrator output voltage.

(8 marks/ markah)

- a) *Terangkan dengan ringkas empat (4) kelebihan meter volt digital berbanding dengan meter volt analog.*
- b) *Penukar analog-ke-digit menggunakan pengamir pada bahagian masukan litar.*
- Lakarkan litar pengamir dengan nilai perintang  $10\text{ k}\Omega$  dan pemuat  $10\text{ }\mu\text{F}$ .*
  - Jika voltan masukan pengamir ialah  $1\text{ V}$ , kirakan voltan keluaran pengamir tersebut selepas  $0.1\text{ saat}$ .*
  - Lakarkan bentuk voltan keluaran pengamir.*

## QUESTION 4 / SOALAN 4

a) With the aid of diagrams, explain **two (2)** transducer functions.

(6 marks/ *markah*)

b) **Figure 3** shows the LVDT and its specification.

- i. Explain briefly the operation of the LVDT.
- ii. Calculate the displacement if the output voltage is 2.5 mV.
- iii. Sketch the graph of the output voltage versus displacement if the output of the LVDT is at the range of -4 mV to +2.5 mV.

(14 marks/ *markah*)

a) Dengan bantuan gambar rajah, terangkan **dua (2)** fungsi transduser.

b) **Rajah 3** menunjukkan LVDT dan spesifikasinya.

- i. Terangkan dengan ringkas prinsip pengendalian LVDT.
- ii. Kirakan anjakan jika voltan keluaran ialah 2.5 mV.
- iii. Lakarkan graf voltan keluaran melawan anjakan jika keluaran LVDT pada julat -4 mV hingga +2.5 mV.


|   |   |                |
|---|---|----------------|
|  | <b>The specification of LVDT is as follow:<br/>Spesifikasi LVDT ialah seperti berikut :</b> |                |
|   | <b>Input voltage /<br/>Voltan masukan</b>   | : 10 V         |
|   | <b>Output voltage /<br/>Voltan keluaran</b>   | : $\pm 5$ mV   |
|   | <b>Displacement range /<br/>Julat anjakan</b>   | : $\pm 5$ inch |

Figure 3 / Rajah 3

## QUESTION 5 / SOALAN 5

a) This question is related to Wien bridge circuit.

- i. Sketch the circuit of Wien bridge circuit.
- ii. Prove that when the bridge is balanced:

$$\frac{R_1}{R_3} + \frac{C_3}{C_1} = \frac{R_2}{R_4}$$

$$f = \frac{1}{2\pi \sqrt{C_1 C_3 R_1 R_3}}$$

- iii. The frequency calculated using the Wien AC bridge is 40 Hz. If  $R_1 = 400 \Omega$ ,  $C_1 = 5.5 \mu\text{F}$  and  $R_3 = R_4 = 1 \text{ k}\Omega$ . Calculate  $C_3$  and  $R_2$ .

(17 marks/ *markah*)

b) List down **three (3)** features of RS232.

(3 marks/ *markah*)

a) *Soalan ini adalah berkaitan dengan litar titi Wien.*

- i. *Lukiskan litar bagi titi Wien.*
- ii. *Buktikan bahawa titi seimbang apabila:*

$$\frac{R_1}{R_3} + \frac{C_3}{C_1} = \frac{R_2}{R_4}$$

$$f = \frac{1}{2\pi \sqrt{C_1 C_3 R_1 R_3}}$$

- iii. *Frekuensi yang dikira dengan menggunakan titi Wien adalah 40 Hz. Jika  $R_1 = 400 \Omega$ ,  $C_1 = 5.5 \mu\text{F}$  dan  $R_3 = R_4 = 1 \text{ k}\Omega$ . Kirakan  $C_3$  and  $R_2$ .*

b) *Senaraikan **tiga (3)** ciri-ciri RS232.*

[100 MARKS / MARKAH]

END OF QUESTION PAPER / KERTAS SOALAN TAMAT

Attachment 1 / Lampiran 1

Measurement and Error / Ralat dan Pengukuran

| <b>Absolute Error, e</b><br><i>Ralat Mutlak, e</i>                    | $Y_n - X_n$  | <b>Standard Deviation</b><br><i>Sisihan Piawaian</i>   | $\sigma = \sqrt{\frac{\sum_{k=1}^n d_k^2}{n-1}}$   |                   |                |             |                                       |             |                                       |                  |                        |           |                        |
|---|--|--|--|-------------------|----------------|-------------|---------------------------------------|-------------|---------------------------------------|------------------|------------------------|-----------|------------------------|
| <b>Percent Error, %e</b><br><i>Peratus Ralat, % e</i>                 | $\frac{e}{Y_n} \times 100\%$                       | <b>Deviation</b><br><i>Sisihan</i>   | $d_1 = x_1 - \bar{x}$ $d_2 = x_2 - \bar{x}$ $d_3 = x_3 - \bar{x}$ <p style="text-align: center;">⋮</p> $d_n = x_n - \bar{x}$ |                   |                |             |                                       |             |                                       |                  |                        |           |                        |
| <b>Accuracy, a</b><br><i>Kejituan, a</i>                              | $100\% - \text{Peratus ralat}$                     | <b>Average deviation</b><br><i>Sisihan purata</i>  | $D = \frac{\sum_{k=1}^n  d_k }{n}$   |                   |                |             |                                       |             |                                       |                  |                        |           |                        |
| <b>Precision</b><br><i>Kebersihan</i>                                 | $1 - \left  \frac{X_n - \bar{X}}{\bar{X}} \right $ | <b>Arithmetic mean / average</b><br><i>Purata / min aritmetik</i>  | $\bar{x} = \frac{\sum_{k=1}^n x_k}{n}$   |                   |                |             |                                       |             |                                       |                  |                        |           |                        |
| <b>Combined Measurement Error</b><br><i>Gabungan ralat pengukuran</i> |  | <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Operasi matematik</th> <th style="text-align: left;">Ralat gabungan</th> </tr> </thead> <tbody> <tr> <td><math>C = A + B</math></td> <td><math>\Delta C = \pm(\Delta A + \Delta B)</math></td> </tr> <tr> <td><math>C = A - B</math></td> <td><math>\Delta C = \pm(\Delta A + \Delta B)</math></td> </tr> <tr> <td><math>C = A \times B</math></td> <td><math>\%C = \pm(\%A + \%B)</math></td> </tr> <tr> <td><math>C = A/B</math></td> <td><math>\%C = \pm(\%A + \%B)</math></td> </tr> </tbody> </table> |  | Operasi matematik | Ralat gabungan | $C = A + B$ | $\Delta C = \pm(\Delta A + \Delta B)$ | $C = A - B$ | $\Delta C = \pm(\Delta A + \Delta B)$ | $C = A \times B$ | $\%C = \pm(\%A + \%B)$ | $C = A/B$ | $\%C = \pm(\%A + \%B)$ |
| Operasi matematik   | Ralat gabungan                                     |  |  |                   |                |             |                                       |             |                                       |                  |                        |           |                        |
| $C = A + B$   | $\Delta C = \pm(\Delta A + \Delta B)$              |  |  |                   |                |             |                                       |             |                                       |                  |                        |           |                        |
| $C = A - B$   | $\Delta C = \pm(\Delta A + \Delta B)$              |  |  |                   |                |             |                                       |             |                                       |                  |                        |           |                        |
| $C = A \times B$  | $\%C = \pm(\%A + \%B)$                             |  |  |                   |                |             |                                       |             |                                       |                  |                        |           |                        |
| $C = A/B$   | $\%C = \pm(\%A + \%B)$                             |  |  |                   |                |             |                                       |             |                                       |                  |                        |           |                        |



## Analog Meter / Meter Analog

|  |  |
|--|--|
| <b>Shunt Resistance</b><br><i>Rintangan Pirau</i>  | $R_{sh} = \frac{V_{sh}}{I_{sh}} = \frac{I_m R_m}{I_{sh}} = \frac{I_m}{I_{sh}} R_m = \frac{I_m}{I - I_m} \times R_m$ <p>Where :<br/> Dimana <math>I = n I_m</math></p>  |
| <b>Aryton Shunt Ampere Meter</b><br><i>Meter Ampere Pirau Aryton</i>   | $R_b + R_c = \frac{I_m (R_{sh} + R_m)}{I_2}$ $R_a = R_{sh} - (R_b + R_c)$ $R_c = \frac{I_m (R_{sh} + R_m)}{I_3}$   |
| <b>Sensitivity</b><br><i>Kepekaan</i>  | $\text{Kepekaan} = \frac{1}{I_{sp}} (\Omega/V)$  |
| <b>Aryton Shunt Voltage Meter</b><br><i>Meter Voltan Pirau Aryton</i>  | $R_a = S \times \text{Julat} - R_m$ $R_b = S \times \text{Julat} - (R_a + R_m)$ $R_c = S \times \text{Julat} - (R_a + R_b + R_m)$  |
| <b>Half-wave Rectifier and Full-wave Rectifier</b><br><i>Penerus Separuh Gelombang dan Penerus Gelombang Penuh</i> | $S_{au} = 0.45 S_{at} \quad \text{or} \quad S_{au} = 0.9 S_{at}$ $R_s = R_T - R_d - \frac{R_m R_{sh}}{R_m + R_{sh}}$ $R_s = R_T - 2 R_d - \frac{R_m R_{sh}}{R_m + R_{sh}}$ <p>Where :<br/> Dimana</p> $I_{sh} = \frac{E_m}{R_{sh}}$ $I_T = I_{sh} + I_m$ $E_{at} = 0.45 V_{pmkd} \text{ or } 0.9 \times V_{pmkd}$ $R_T = \frac{E_{at}}{I_T}$ |

## Digital Instruments / Alatan Digital

|   |  |
|---|--|
| <b>Single Slope Converter Techniques</b><br><b>Teknik Penukar Satu Cerun</b>                  | $V_x = V_{ref} \times \frac{t_1}{t_1 + t_2}$ <p>Bilangan denyut = <math>t \times f</math></p>  |
| <b>Dual Slope Converter Techniques</b><br><b>Teknik Penukar Dua Cerun</b>                     | <b>Capasitor Charging Pemuat Mengecas</b><br>$V_A = V_i \frac{t_2 - t_1}{RC}$<br><b>Capasitor Charging Pemuat Mengecas</b><br>$V_A = V_{ref} \frac{t_3 - t_2}{RC}$ |
| <b>Voltage to Frequency Converter Techniques</b><br><b>Teknik Penukar Voltan ke Frekuensi</b> | $V_i = \frac{f}{50} \quad f = \frac{\text{Bilangan denyut}}{\text{Masa denyutan}}$   |

## Transducers / Tranduser

|   |   |
|---|---|
| <b>Strain Gauge</b><br><b>Tolok Terikan</b>   | $K = \frac{\Delta R/R}{\Delta l/l} \quad G = \frac{\Delta l}{l} \quad F = SA$ $\Delta R = KRG \quad S = GE$ |
| <b>Linear Variable Displacement Transducer (LVDT)</b><br><b>Pengubah Kebezaan Boleh Ubah Lelurus (LVDT)</b> | $v_o = v_1 - v_2$ <p><math>V_o = \text{Kepekaan} \times V_{in} \times \text{Anjakan}</math></p>             |
| <b>Thermocouple</b><br><b>Pengganding Suhu</b>  | $V_m = V_o + V_r$ $V_o = AT^2 + BT^2$   |
| <b>Resistance Temperature Detector (RTD)</b><br><b>Pengesan Suhu Rintangan (RTD)</b>                        | $R = R_o (1 + \alpha \Delta T)$   |
| <b>Termistor</b><br><b>Suhu Rintangan</b>   | $R = R_o e^{\beta \left( \frac{1}{T} - \frac{1}{T_o} \right)}$  |

## Signal Conditioning / Penyesuaian Isyarat

| Direct Current Bridge<br><i>Titi Arus Terus</i>  |  |  |
|--|--|--|
| Wheatstone Quarter Bridge<br><i>Titi Suku Wheatstone</i>   | Wheatstone Half Bridge<br><i>Titi Separuh Wheatstone</i>   | Wheatstone Full Bridge<br><i>Titi Penuh Wheatstone</i> |
| $\frac{\Delta R}{4R} E$  | $\frac{\Delta R}{2R} E$  | $\frac{\Delta R}{R} E$                                 |
| Alternatif Current Bridge<br><i>Titi Arus Ulang Alik</i>   |  |  |
| Maxwell Bridge<br><i>Titi Maxwell</i>  | Hay Bridge<br><i>Titi Hay</i>  |  |
| $\frac{1}{Z_1} = \frac{1}{R_1} + j\omega C_1$<br>$Z_2 = R_2$<br>$Z_3 = R_3$<br>$Z_x = R_x + j\omega L_x$                             | $Z_1 = R_1 + \frac{1}{j\omega C_1}$<br>$Z_2 = R_2$<br>$Z_3 = R_3$<br>$Z_x = R_x + j\omega L_x$                     |  |
| Schering Bridge<br><i>Titi Schering</i>  | Wien Bridge<br><i>Titi Wien</i>  |  |
| $\frac{1}{Z_1} = \frac{1}{R_1} + j\omega C_1$<br>$Z_2 = R_2$<br>$Z_3 = \frac{1}{j\omega C_3}$<br>$Z_x = R_x + \frac{1}{j\omega C_x}$ | $Z_1 = R_1 + \frac{1}{j\omega C_1}$<br>$Z_2 = R_2$<br>$\frac{1}{Z_3} = \frac{1}{R_3} + j\omega C_3$<br>$Z_4 = R_4$ |  |

