



KOLEJ YAYASAN PELAJARAN JOHOR
FINAL EXAMINATION

COURSE NAME : CIRCUIT ANALYZE
COURSE CODE : DKE 2093
SESSION : JUNE 2023
DURATION : 2 HOURS 30 MINUTES

INSTRUCTION TO CANDIDATES /
ARAHAH KEPADA CALON

1. This examination paper consists of **SIX (6)** questions. Answer **ALL** questions. /
*Kertas soalan ini mengandungi **ENAM (6)** soalan. Jawab **SEMUA** soalan.*
2. Candidates are not allowed to bring any material/note to the examination hall/room except with the permission from the invigilator. /
Calon tidak dibenarkan untuk membawa sebarang bahan/nota ke dewan/bilik peperiksaan tanpa kebenaran daripada pengawas.
3. Please check to make sure that this examination pack consist of: /
Pastikan kertas soalan peperiksaan ini mengandungi:
 - i. The Question Paper /
Kertas Soalan
 - ii. An Answering Booklet /
Buku Jawapan
 - iii. Attachment 1 /
Lampiran 1
 - iv. Semilog Paper/
Kertas Semilog

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JANGAN BUKA KERTAS SOALANINI SEHINGGA DIBERITAHU

This examination paper consists of 11 printed pages including front page
Kertas soalan ini mengandungi 11 halaman bercetak termasuk muka hadapan



This examination paper consists of **SIX (6)** questions. Answer **ALL** the questions in the Answering Booklet.

*Kertas soalan ini mengandungi **ENAM (6)** soalan. Jawab **SEMUA** soalan dalam Buku Jawapan.*

QUESTION 1 / SOALAN 1

Figure 1 shows five (5) interconnected inductors. The initial currents for two (2) of the inductors are also shown in Figure 1. Looking from terminal A - B.

- Find the equivalent inductance, L_{eq} .
- Find the initial current, i in the inductive network.
- Find the energy stored in equivalent inductance, L_{eq} .

(10 marks/ markah)

Rajah 1 menunjukkan lima (5) pearuh yang saling dihubungkan. Arus awalan bagi dua (2) pearuh juga ditunjukkan dalam Rajah 1. Dilihat dari terminal A - B.

- Dapatkan kearuhan setara, L_{eq} .
- Dapatkan arus awalan, i dalam rangkaian pearuh.
- Dapatkan tenaga yang disimpan di dalam kearuhan setara, L_{eq} .

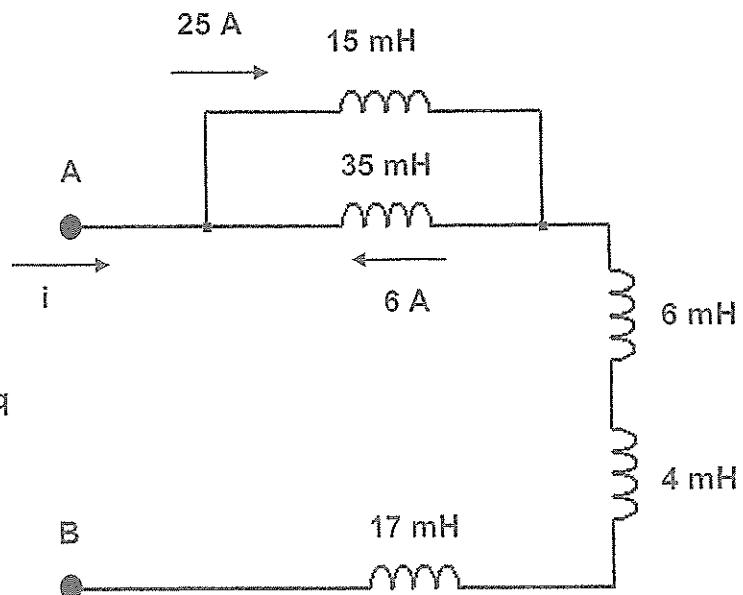


Figure 1 / Rajah 1

QUESTION 2 / SOALAN 2

The circuit in **Figure 2** is in steady state at $t < 0$. Find $v(t)$ for $t > 0$ using transient analysis method.

(15 marks/ markah)

Litar dalam **Rajah 2** berada dalam keadaan mantap pada $t < 0$. Cari $v(t)$ untuk $t > 0$ menggunakan kaedah analisis ubahsua.

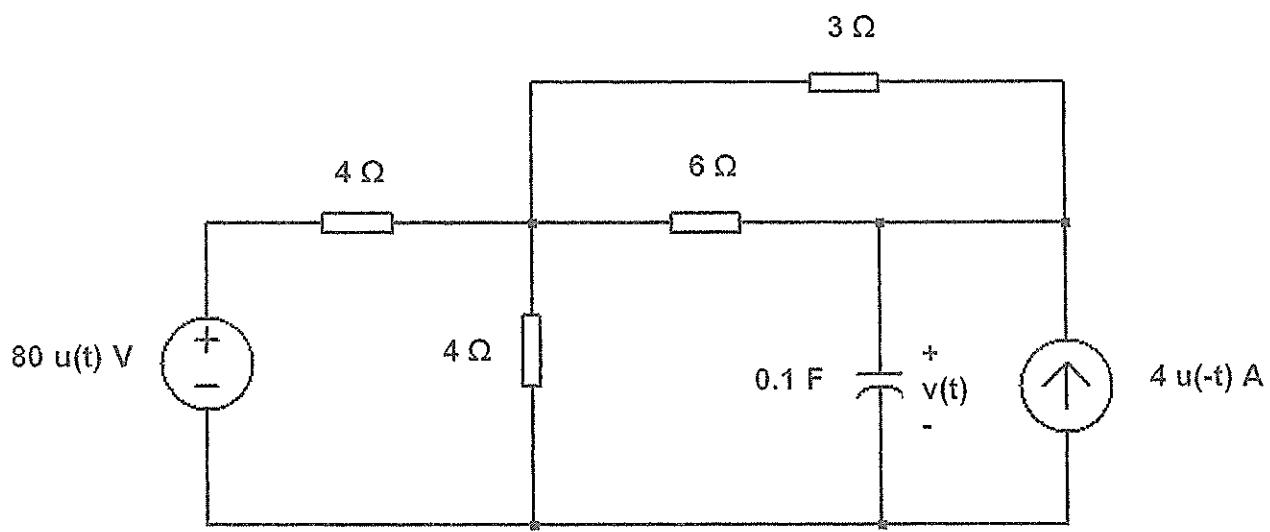


Figure 2 / Rajah 2

QUESTION 3 / SOALAN 3

Referring to Figure 3, the switch is closed at $t = 0$. Find $i(t)$ and $i_R(t)$ for $t \geq 0$.

(25 marks/ markah)

Merujuk kepada Rajah 3, suis ditutup pada $t = 0$. Dapatkan $i(t)$ dan $i_R(t)$ untuk $t \geq 0$.

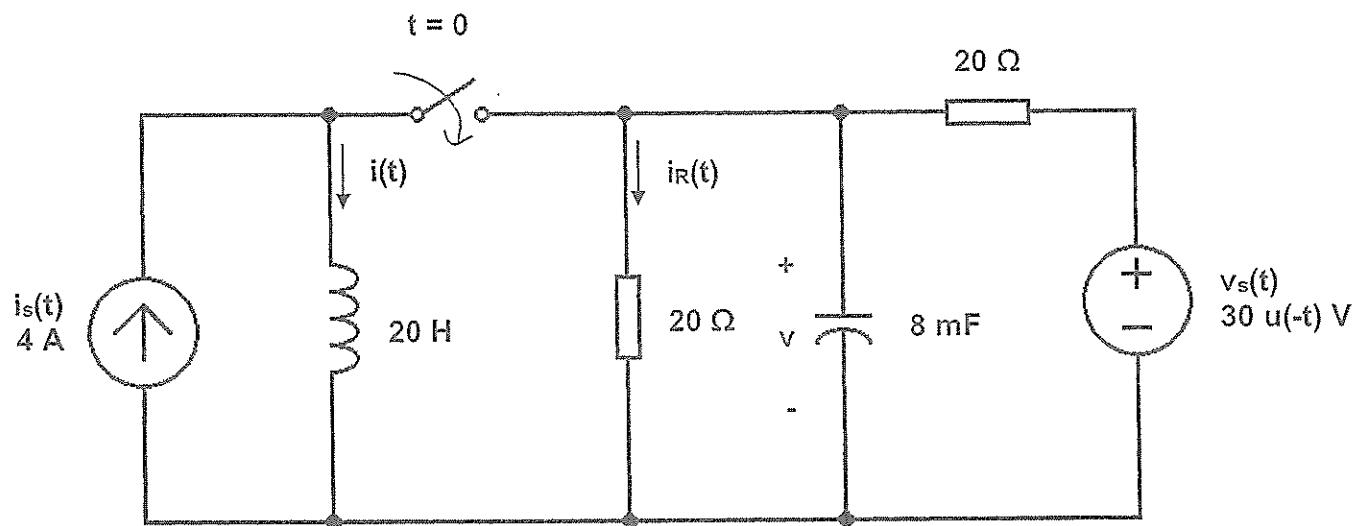


Figure 3 / Rajah 3

QUESTION 4 / SOALAN 4

Find $v_o(t)$ in the Figure 4, assuming zero initial conditions.

(15 marks/ markah)

Cari $v_o(t)$ dalam Rajah 4, dengan mengandaikan keadaan awal adalah sifar.

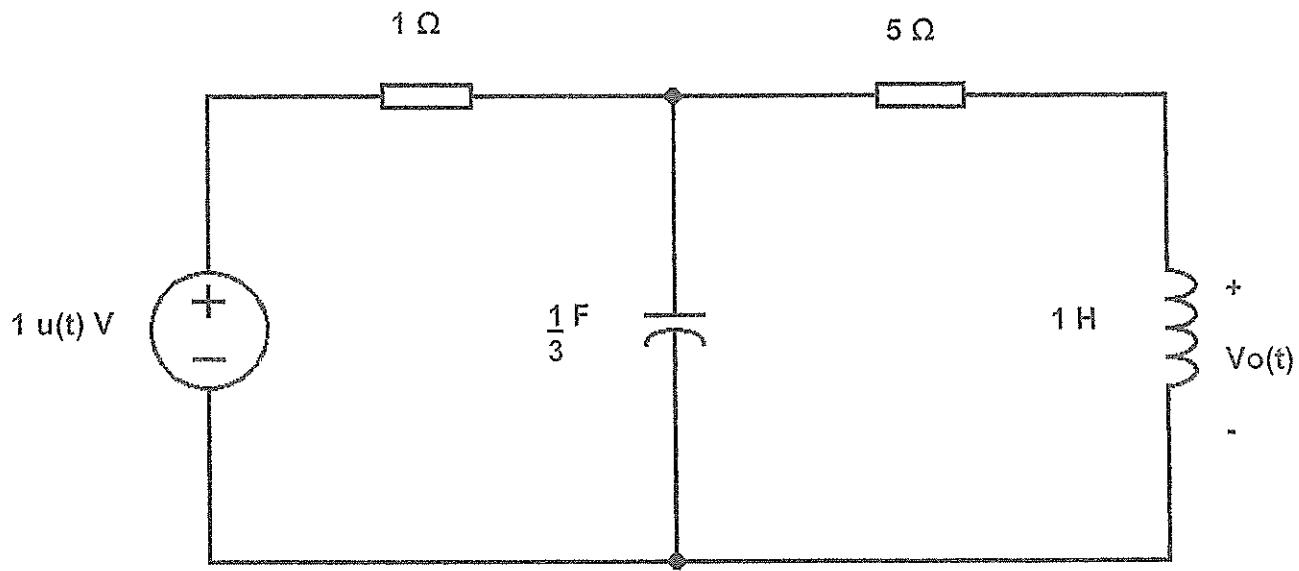


Figure 4 / Rajah 4

QUESTION 5 / SOALAN 5

Draw the magnitude Bode Plot for the following transfer function:

$$H(s) = \frac{10(s+5)}{(s+2)(s^2 + 2s + 4)}$$

Use minimum frequency, $\omega=0.1$ radian/second and maximum frequency, $\omega=10,000$ radian/second.

(15 marks/ markah)

Lukis Plot Bode magnitud untuk rangkap pindah berikut:

$$H(s) = \frac{10(s+5)}{(s+2)(s^2 + 2s + 4)}$$

Guna frekuensi minima, $\omega=0.1$ radian/saat dan frekuensi maksima, $\omega=10,000$ radian/saat.

QUESTION 6 / SOALAN 6

Obtain the z-parameters for the network in Figure 5 as function of s.

(20 marks/ markah)

Dapatkan parameter-z untuk rangkaian dalam Rajah 5 sebagai fungsi s.

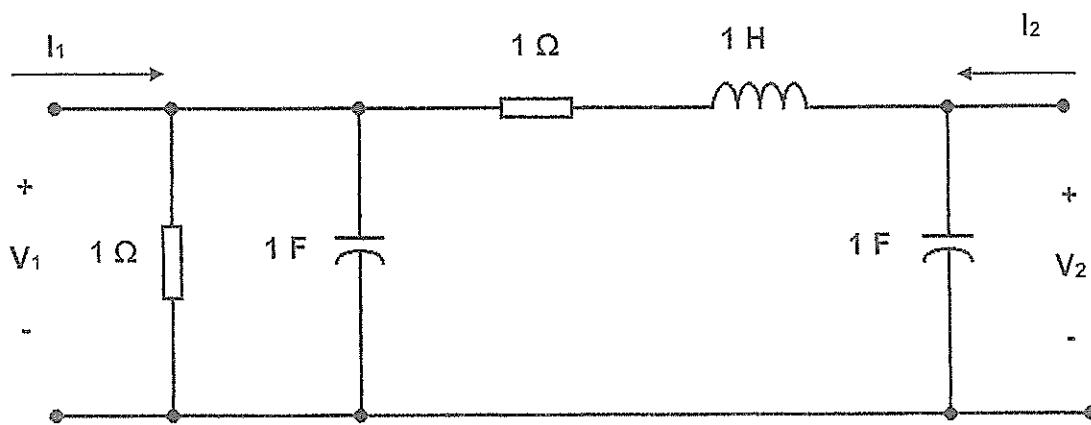


Figure 5 / Rajah 5

[100 MARKS/ MARKAH]

END OF QUESTION PAPER / KERTAS SOALAN TAMAT

Attachment 1 / Lampiran 1

Forcing Functions and Their Assumed Solutions
Fungsi Berdaya dan Penyelesaian Anggapan

Forcing function <i>/ Fungsi Berdaya</i>		Assumed Solution / <i>Penyelesaian Anggapan</i>	
Constan / Malar	$f(t) = A$	$x_f(t) = K_2$	
Exponential/ Eksponen	$f(t) = M e^{-st}$	$x_f(t) = K_2 e^{-st}$	
Variable/ Pembolehubah	Ramp/ Tanjak	$f(t) = mt$	$x_f(t) = K_2 t + K_3$
	Parabolic/ Parabola	$f(t) = t^2$	$x_f(t) = K_2 t^2 + K_3 t + K_4$
Sinusoidal/ Sinus		$f(t) = M \sin(\omega t + \theta)$	
		$f(t) = M \cos(\omega t + \theta)$	
Exponential Sinusoidal/ Sinus Eksponen		$f(t) = M e^{-st} \sin(\omega t + \theta)$	
		$x_f(t) = e^{-st} (K_2 \sin \omega t + K_3 \cos \omega t)$	

Table of Laplace Transform Pairs
Jadual Penukaran Pasangan Jelmaan Laplace

Function/ Rangkap	$f(t)$	$F(s)$
Unit Impulse/ Dedenyut	$\delta(t)$	1
Unit Step/ Unit langkah Constant / Malar	$u(t)$ 1	$\frac{1}{s}$
Unit Ramp/ Unit Tanjak t function / Rangkap t	$t u(t)$	$\frac{1}{s^2}$
Unit Parabolic / Unit Parabola	$\frac{1}{2} t^2 u(t)$	$\frac{1}{s^3}$
n^{th} integral of impulse/ Kamiran ke- n dedenyut	$\delta^{-n}(t)$	$\frac{1}{s^n}$
n^{th} derivative of impulse/ Kerbezaan ke- n dedenyut	$\delta^n(t)$	s^n
Power of t / Kuasa t	$\frac{t^{n-1}}{(n-1)!}$	$\frac{1}{s^n}$
Exponential / Eksponen	e^{-at}	$\frac{1}{s+a}$
t -multiplication exponential/ Pendaraban t bagi eksponen	$t e^{-at}$	$\frac{1}{(s+a)^2}$
Repeated t -multiplication exponential/ Pendaraban t berulang bagi eksponen	$\frac{1}{(n-1)!} t^{n-1} e^{-at}$	$\frac{1}{(s+a)^n}$
Sine/ Sinus	$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$
Cosine/ Kosinus	$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
Damped sine/ Sinus teredam	$e^{-at} \sin \omega t$	$\frac{\omega}{(s+a)^2 + \omega^2}$

Damped cosine/ Kosinus teredam	$e^{-at} \cos \omega t$	$\frac{s+a}{(s+a)^2 + \omega^2}$
t -multipllicated sine <i>Pendaraban t bagi sinus</i>	$t \sin \omega t$	$\frac{2\omega s}{(s^2 + \omega^2)^2}$
t -multipllicated cosine <i>Pendaraban t bagi kosinus</i>	$t \cos \omega t$	$\frac{s^2 - \omega^2}{(s^2 + \omega^2)^2}$

Two-Port Network Parameters
Parameter Rangkaian Dua Liang

Impedance parameters

$$V_1 = z_{11} I_1 + z_{12} I_2$$

$$V_2 = z_{21} I_1 + z_{22} I_2$$

Admittance parameters

$$I_1 = y_{11} V_1 + y_{12} V_2$$

$$I_2 = y_{21} V_1 + y_{22} V_2$$

Hybrid parameters

$$V_1 = h_{11} I_1 + h_{12} V_2$$

$$I_2 = h_{21} I_1 + h_{22} V_2$$

Transmission parameters

$$V_1 = AV_2 - BI_2$$

$$I_1 = CV_2 - DI_2$$

Conversion Table for Two-Port Network Parameters
Jadual Penukaran Untuk Rangkaian Dua Liang

	Z		Y		h		ABCD	
Z	z_{11} z_{12}		$\frac{y_{22}}{\Delta_y}$ $\frac{-y_{12}}{\Delta_y}$		$\frac{\Delta_h}{h_{22}}$ $\frac{h_{12}}{h_{22}}$		$\frac{A}{C}$ $\frac{\Delta_T}{C}$	
	z_{21}	z_{22}	$\frac{-y_{21}}{\Delta_y}$	$\frac{y_{11}}{\Delta_y}$	$\frac{-h_{21}}{h_{22}}$	$\frac{1}{h_{22}}$	$\frac{1}{C}$	$\frac{D}{C}$
Y	$\frac{z_{22}}{\Delta_z}$	$\frac{-z_{12}}{\Delta_z}$	y_{11}	y_{12}	$\frac{1}{h_{11}}$	$\frac{-h_{12}}{h_{11}}$	$\frac{D}{B}$	$\frac{-\Delta_T}{B}$
	$\frac{-z_{21}}{\Delta_z}$	$\frac{z_{11}}{\Delta_z}$	y_{21}	y_{22}	$\frac{h_{21}}{h_{11}}$	$\frac{\Delta_h}{h_{11}}$	$\frac{-1}{B}$	$\frac{A}{B}$
h	$\frac{\Delta_z}{z_{22}}$	$\frac{z_{12}}{z_{22}}$	$\frac{1}{y_{11}}$	$\frac{-y_{12}}{y_{11}}$	h_{11}	h_{12}	$\frac{B}{D}$	$\frac{\Delta_T}{D}$
	$\frac{-z_{21}}{z_{22}}$	$\frac{1}{z_{22}}$	$\frac{y_{21}}{y_{11}}$	$\frac{\Delta_y}{y_{11}}$	h_{21}	h_{22}	$\frac{-1}{D}$	$\frac{C}{D}$
ABCD	$\frac{z_{11}}{z_{21}}$	$\frac{\Delta_z}{z_{21}}$	$\frac{-y_{22}}{y_{21}}$	$\frac{-1}{y_{21}}$	$\frac{-\Delta_h}{h_{21}}$	$\frac{-h_{11}}{h_{21}}$	A	B
	$\frac{1}{z_{21}}$	$\frac{z_{22}}{z_{21}}$	$\frac{-\Delta_y}{y_{21}}$	$\frac{-y_{11}}{y_{21}}$	$\frac{-h_{22}}{h_{21}}$	$\frac{-1}{h_{21}}$	C	D



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